

modo TE₁₁ in guida circolare

modo TE₁₁^(e)

$$\kappa_{11}'' = x'_{11} / a \approx 1.841 / a$$

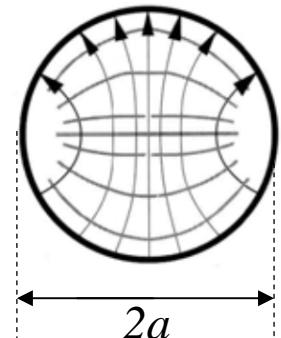
$$\lambda_{11}'' = 2\pi a / x'_{11} \approx 3.412 a$$

$$\Phi_{11}''^{(e)} = F_{11}'' J_1(\kappa_{11}'' r) \cos \varphi$$

$$\vec{e}_{11}''^{(e)} = F_{11}'' \left(\vec{u}_r \frac{J_1(\kappa_{11}'' r)}{\kappa_{11}'' r} \sin \varphi + \vec{u}_\varphi J'_1(\kappa_{11}'' r) \cos \varphi \right)$$

$$\vec{h}_{11}''^{(e)} = F_{11}'' \left(-\vec{u}_r J'_m(\kappa_{11}'' r) \cos \varphi + \vec{u}_\varphi \frac{J_1(\kappa_{11}'' r)}{\kappa_{11}'' r} \sin \varphi \right)$$

$$F_{11}'' = \frac{\sqrt{2} \kappa_{11}''}{J_1(x'_{11}) \sqrt{\pi (x'^2_{11} - 1)}} \approx \frac{1.633}{a}$$



le espressioni del potenziale e dei vettori modali relativi al modo dispari si deducono dalle precedenti cambiando $\cos \varphi \rightarrow \sin \varphi$ e $\sin \varphi \rightarrow -\cos \varphi$.

campi modali

$$\vec{E}_{11}'' = \vec{e}_{11}''^{(e)} V_{11}''^{(e)}(z) + \vec{e}_{11}''^{(o)} V_{11}''^{(o)}(z)$$

$$\vec{H}_{11}'' = \vec{h}_{11}''^{(e)} I_{11}''^{(e)}(z) + \vec{h}_{11}''^{(o)} I_{11}''^{(o)}(z) - j \vec{u}_z \frac{\lambda}{\lambda_{11}''} \left(\Phi_{11}''^{(e)} \frac{V_{11}''^{(e)}(z)}{\eta} + \Phi_{11}''^{(o)} \frac{V_{11}''^{(o)}(z)}{\eta} \right)$$

$$\lambda > \lambda_{11}''$$

$$\alpha = \frac{2\pi}{\lambda_{11}''} \sqrt{1 - \left(\frac{\lambda_{11}''}{\lambda}\right)^2}$$

$$Z = \frac{j\eta}{\sqrt{\left(\frac{\lambda_{11}''}{\lambda}\right)^2 - 1}}$$

$$\lambda < \lambda_{11}''$$

$$\beta = \frac{2\pi}{\lambda} \sqrt{1 - \left(\frac{\lambda}{\lambda_{11}''}\right)^2}$$

$$Z = \frac{\eta}{\sqrt{1 - \left(\frac{\lambda_{11}''}{\lambda}\right)^2}}$$

